

Disk Layout

- "Platter" Circular Piece of Magnetic Material Coated Aluminum
- One Platter Has 2 "Sides"
- Each Side is Divided into Concentric Rings Called "Tracks"
- Each Track is Divided into Arcs Called "Sectors"
- Each Sector Can Store Some Number of "Bytes" of Data
 "Media Canacity" Determines Amount of Storage per Sector
- "Media Capacity" Determines Amount of Storage per Sector



Physical Disk Coordinates

- A Platter can be "Double Sided" or "Single Sided"
- A Single Fixed Disk can Contain Multiple Platters
- Need Three-Dimensional Coordinate
- A Stack of Tracks On Top of Each Other is a "Cylinder"
- Each Side of a Platter Must Have a "Read/Write Head"
 Contains Induction Coll Floats Over Surface
 (Except for Floppy Where it Actually Touches)
- Position of Read/Write Head Given by "Cylinder" Number

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• Physical Location on Disk: <cylinder, head, sector>





Disk Performance - Bandwidth

- "Seek Time" (Average) Time Required to Position R/W Head Over a Track/Sector (5-15 ms)
- "Rotational Latency"- After Seek Wait for Sector to be Under RW Head Typical Disks Rotate at 3600, 5400, 7200, 10800 RPM Average Rotational Latency = 1/2 Rotation (4-8ms)

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- "Transfer Time" Time for 1 Sector of Data to be Read/Written After Seek and Rotational Latency (25-50µs)
- "Access Time" is Sum of Above Dominated by Seek and Rotational Latency BR

Disk Performance - Capacity

•	"Linear Bit Density" - Number of Bits/cm that can be Stored Along a Track
•	Linear Bit Density (Typically 50,000-100,000 bits/cm) Depends on:

Purity of Magnetizable Media

Air Quality

Data Encoding

• "Winchester Disk" - Sealed at Factory to Preserve Air/Surface Quality -First "Winchester Disk" Was 30 MB Fixed and 30 MB Removable (IBM)

-.30-30 Winchester

"Unformatted Capacity" - Disregards Preamble, ECC and Intersector Gap BR

-Marketing Hype





Disk Controllers

Each Disk Drive Has a Controller Associated With It
 Purpose of Controller:

- 1) Accept Commands from Software (READ, WRITE, FORMAT)
- 2) Control Arm Motion
- 3) Detect/Correct Errors
- 4) Convert parallel data into Serial Bit-Stream (vice-versa)5) Remap bad Sectors to Spares (each track has spares)

6) Caching Sectors

IDE – "Integrated Drive Electronics" – Most Controller Functionality
 is Inside the Drive Enclosure

• EIDE – "Extended IDE"

• SCSI – "Small Computer System Interface" – Actually a Bus 4/1601 Standard – Disk Media is Same

Some Calculations

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Assume a disk has a read/write bandwidth of 5 MB/s average (transfer rate).

Assume that seek time + rotational latency is 10 ms.

What % of the bandwidth of a 20MB/s SCSI bus is used for a 64KB transfer?

IO transfer rate = Transfer size/Transfer time = 64KB/22.8 ms = 2.74 MB/s

% bandwidth needed = ~IO transfer rate/ Bus transfer rate = 2.74~MB/s~/~20~MB/s~=~13.7%

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RAID Levels

- Level 0: simply parallel disks in which data is striped with no redundancy
- Level 1: data is mirrored to 2nd disk. Requires twice as many disks as level 0. Can survive 1 disk failure.
- Level 3: data is striped at byte level across several drives, one drive holds checksum information that allows recovery from one failed drive (including checksum drive).
- Level 5: data is striped at block level across several drives, and parity is also distributed.
 - Better than level 3 for multiprocessing systems because can support multiple concurrent read accesses if data is limited to block size.

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